Analysis-III

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## Solutions to selected exercises

**3e3 Exercise.** Consider the set  $U \subset \mathbb{R}^n$  of all  $(a_0, \ldots, a_{n-1})$  such that the polynomial

$$t \mapsto t^n + a_{n-1}t^{n-1} + \dots + a_0$$

has n pairwise distinct real roots.

(a) Prove that U is open.

(b) Define  $\psi : U \to \mathbb{R}^n$  by  $\psi(a_0, \ldots, a_{n-1}) = (t_1, \ldots, t_n)$  where  $t_1 < \cdots < t_n$  are the roots of the polynomial. Prove that  $\psi$  is a homeomorphism  $U \to V$  where  $V = \{(t_1, \ldots, t_n) : t_1 < \cdots < t_n\}$ .<sup>1</sup>

## Solution.

The set V is open (evidently). We consider a mapping  $\varphi: V \to U$  defined by

$$\varphi(t_1, \dots, t_n) = (a_0, \dots, a_{n-1})$$
 whenever  
 $\forall x \ (t - t_1) \dots (t - t_n) = t^n + a_{n-1}t^{n-1} + \dots + a_0.$ 

It is continuously differentiable, since each  $a_k$  is a polynomial function of  $t_1, \ldots, t_n$ . We note that  $\varphi(t_1, \ldots, t_n) = (a_0, \ldots, a_{n-1})$  if and only if  $\psi(a_0, \ldots, a_{n-1}) = (t_1, \ldots, t_n)$ ; that is,  $\varphi^{-1} = \psi$ .

According to the hint we use 2e9(b). Treating  $a_0, \ldots, a_{n-1}$  as coordinates in the space  $S_n$  of 2e9 we have

the operator  $(D\varphi)_{(t_1,\ldots,t_n)}$  is invertible

for all  $(t_1, \ldots, t_n) \in V$ .

By Theorem 4c1 applied to  $\varphi$  near an arbitrary point  $v \in V$ , the set  $\varphi(V) = U$  is a neighborhood of  $\varphi(v) = u$ , and the mapping  $\varphi^{-1} = \psi$  is continuous at u.

This holds for every  $u \in U$ ; thus U is open, and  $\psi$  is continuous. Taking into account continuity of  $\psi^{-1} = \varphi$  we see that  $\psi$  is a homeomorphism.  $\Box$ 

**3i1 Exercise.** Let A be an invertible linear operator. Find  $||A^{-1}||$ .

**Solution.** Using 1e1 and taking  $x = A^{-1}y$  we have

$$||A^{-1}|| = \sup_{y \in \mathbb{R}^{n}, y \neq 0} \frac{|A^{-1}y|}{|y|} = \sup_{x \in \mathbb{R}^{n}, x \neq 0} \frac{|x|}{|Ax|};$$
$$\frac{1}{||A^{-1}||} = \inf_{x \in \mathbb{R}^{n}, x \neq 0} \frac{|Ax|}{|x|} = \min_{|x|=1} |Ax|.$$

<sup>1</sup>Hint: use 2e9(b).

## Analysis-III

It was shown before Exercise 3i1 that  $\max_{|x|=1} |Ax|^2$  is the maximal eigenvalue  $\lambda_{\max}$  of  $A^*A$ . Similarly,  $\min_{|x|=1} |Ax|^2$  is the minimal eigenvalue  $\lambda_{\min}$  of  $A^*A$ . Thus,  $||A^{-1}||^2 = 1/\lambda_{\min}$ .

**4c9 Exercise.** (a) Let  $f: U \to V$  be as in Theorem 4c5 and in addition  $f \in C^2(U)$  (recall Sect. 2g). Prove that  $f^{-1} \in C^2(V)$ .<sup>1</sup>

(b) The same for  $C^k(\ldots)$  where  $k = 3, 4, \ldots$ 

**Solution.** (a) Denote  $g = f^{-1}$ . The mapping  $y \mapsto (Dg)_y = ((Df)_{g(y)})^{-1}$ is the composition of three mappings. First,  $y \mapsto g(y) = x$ . Second,  $x \mapsto (Df)_x = A$ . Third,  $A \mapsto A^{-1}$ . The first mapping  $g : V \to U$  is continuously differentiable by Theorem 4c5. The second mapping is continuously differentiable on U since  $f \in C^2(U)$ . The third mapping is continuously differentiable, see 4c8. Therefore their composition  $y \mapsto (Dg)_y$  is continuously differentiable, which means that  $g \in C^2(V)$ .

(b) Induction in k. By the induction hypothesis, the first mapping g belongs to  $C^{k-1}(V)$ . The second mapping  $x \mapsto (Df)_x$  belongs to  $C^{k-1}(U)$  since  $f \in C^k(U)$ . The third mapping  $A \mapsto A^{-1}$  belongs to  $C^m$  for all m, since elements of  $A^{-1}$  are just rational functions (that is, fractions of polynomials) of the elements of A (as noted in 4c8). Therefore their composition belongs to  $C^{k-1}$ , which means that  $g \in C^k(V)$ .

<sup>&</sup>lt;sup>1</sup>Hint:  $(Dg)_y = ((Df)_{g(y)})^{-1}$  where  $g = f^{-1}$ .