

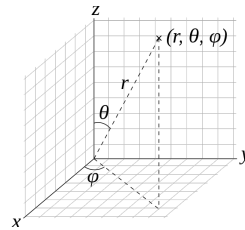
9 Radon-Nikodym theorem and conditioning

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9a Borel-Kolmogorov paradox

Spherical coordinates on \mathbb{R}^3 may be treated as a map $\alpha : (r, \theta, \varphi) \mapsto (x, y, z)$ where¹

$$(9a1) \quad \begin{aligned} x &= r \sin \theta \cos \varphi, \\ y &= r \sin \theta \sin \varphi, \\ z &= r \cos \theta; \end{aligned}$$



this is a homeomorphism (moreover, diffeomorphism) between two open sets in \mathbb{R}^3 :

$$(0, \infty) \times (0, \pi) \times (-\pi, \pi) \rightarrow \mathbb{R}^3 \setminus ((-\infty, 0] \times \{0\} \times \mathbb{R}).$$

It does not preserve Lebesgue measure m ; rather, m is the image of the measure²

$$((r, \theta, \varphi) \mapsto r^2 \sin \theta) \cdot m.$$

Less formally, one writes

$$dx \, dy \, dz = r^2 \sin \theta \, dr \, d\theta \, d\varphi = (r^2 \, dr)(\sin \theta \, d\theta)(d\varphi),$$

a product measure. And the uniform distribution on the ball $x^2 + y^2 + z^2 < 1$ turns into the product of three probability measures

$$\frac{3}{4\pi} dx \, dy \, dz = (3r^2 \, dr) \left(\frac{1}{2} \sin \theta \, d\theta\right) \left(\frac{1}{2\pi} d\varphi\right)$$

¹Picture from Wikipedia.

²See also Footnote 1 on page 100.

on $(0, 1) \times (0, \pi) \times (-\pi, \pi)$.

According to Sect. 6d, the conditional distribution on the sphere $x^2 + y^2 + z^2 = 1$ (that is, $r = 1$) is given by $(\frac{1}{2} \sin \theta d\theta)(\frac{1}{2\pi} d\varphi)$. Further, the conditional distribution on the circle $x^2 + y^2 = 1$, $z = 0$ (that is, $r = 1$, $\theta = \frac{\pi}{2}$, the equator) is given by $\frac{1}{2\pi} d\varphi$. And the conditional distribution on the half-circle $x^2 + z^2 = 1$, $y = 0$, $x > 0$ (that is, $r = 1$, $\varphi = 0$, a line of longitude) is given by $\frac{1}{2} \sin \theta d\theta$.

Quite strange: the result is not invariant under rotations of \mathbb{R}^3 ; why?¹

9b Radon-Nikodym theorem

9b1 Definition. Let (X, S, μ) be a measure space. A measure ν on (X, S) is *absolutely continuous* (w.r.t. μ), in symbols $\nu \ll \mu$, if

$$\forall A \in S \quad (\mu(A) = 0 \implies \nu(A) = 0).$$

If $\nu = f \cdot \mu$ for some measurable $f : X \rightarrow [0, \infty]$, then $\nu \ll \mu$ (recall Sect. 4c). If μ is σ -finite and $\nu = f \cdot \mu$ for some measurable $f : X \rightarrow [0, \infty)$, then ν is σ -finite (by 4c10(b)) and $\nu \ll \mu$. Here is the converse.

9b2 Theorem (Radon-Nikodym). Let (X, S, μ) be a σ -finite measure space, and ν an absolutely continuous (w.r.t. μ) σ -finite measure on (X, S) . Then $\nu = f \cdot \mu$ for some measurable $f : X \rightarrow [0, \infty)$.

9b3 Remark. If ν is not σ -finite, then still $\nu = f \cdot \mu$, but $f : X \rightarrow [0, \infty]$.

This claim fails badly without σ -finiteness of μ .

9b4 Exercise. Let (X, S) be $[0, 1]$ with Borel σ -algebra, and ν the Lebesgue measure on it. Prove that ν is not of the form $f \cdot \mu$, if

- (a) μ is the counting measure;
- (b) $\mu = \infty \cdot \nu$.

9b5 Remark. Uniqueness of f (up to equivalence) is ensured by 7a4.

Proof of Th. 9b2 and Remark 9b3. WLOG, $\mu(X) < \infty$. Indeed, a σ -finite μ is equivalent to some finite measure μ_1 (by 5b8), and $\nu \ll \mu \iff \nu \ll \mu_1$ (since μ and μ_1 have the same null sets, as noted before 5b7); also, $\nu = f \cdot \mu_1 \iff \nu = f \frac{d\mu_1}{d\mu} \cdot \mu$ (by 4b7).

• From now on, μ is finite.

¹“Many quite futile arguments have raged between otherwise competent probabilists over which of these results is ‘correct’.” E.T. Jaynes (quote from Wikipedia).

If ν is not σ -finite, we take $A_n \in S$ such that $\nu(A_n) < \infty$ and $\mu(A_n) \rightarrow \sup_{\nu(A) < \infty} \mu(A)$; we introduce $A_\infty = \cup_n A_n$. Clearly, ν is σ -finite on A_∞ ; and $\nu = \infty \cdot \mu$ on $X \setminus A_\infty$ (think, why). Thus, 9b2 implies that $\nu = f \cdot \mu$ for some measurable $f : X \rightarrow [0, \infty]$.

Given a σ -finite ν , we may assume WLOG that ν is finite (similarly to μ).

- From now on, also ν is finite.

If $\nu = f \cdot (\mu + \nu)$ for some f , then $(1 - f) \cdot \nu = f \cdot \mu$, and $1 - f > 0$ μ -a.e.; $\nu \ll \mu$ implies $1 - f > 0$ ν -a.e. (think, why), therefore $\nu = \frac{f}{1-f} \cdot \mu$.

- From now on, in addition, $\nu \leq \mu$.

We need f such that $\nu(A) = (f \cdot \mu)(A) = \int f \mathbb{1}_A d\mu = \langle f, \mathbb{1}_A \rangle_\mu$ for all $A \in S$; here the inner product is taken in $L_2(\mu)$. It is sufficient to find $f \in L_2(\mu)$ such that $\langle f, g \rangle_\mu = \int g d\nu$ for all $g \in L_2(\mu)$ (then surely $f \geq 0$). Taking into account that $|\int g d\nu| = |\langle g, \mathbb{1} \rangle_\nu| \leq \|g\|_\nu \|\mathbb{1}\|_\nu = \sqrt{\nu(X)} \int g^2 d\nu \leq \sqrt{\nu(X)} \int g^2 d\mu = \sqrt{\nu(X)} \|g\|_\mu$ we see that the linear functional $\ell : L_2(\mu) \rightarrow \mathbb{R}$ defined by $\ell(g) = \int g d\nu$ is bounded. Thus, Th. 9b2 is reduced to the following well-known fact from the theory of Hilbert spaces. \square

9b6 Lemma. For every bounded linear functional ℓ on $L_2(\mu)$ there exists $f \in L_2(\mu)$ such that

$$\forall g \in L_2(\mu) \quad \ell(g) = \langle f, g \rangle.$$

Usually, $L_2(\mu)$ is separable, therefore has an orthonormal basis $(e_n)_n$, and we just take

$$f = \sum_n \ell(e_n) e_n$$

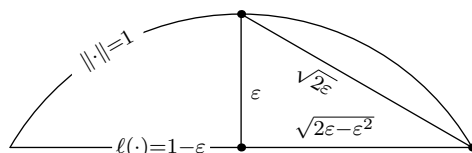
(it converges; think, why); then $\ell(g) = \langle f, g \rangle$ for $g = e_n$, therefore, for all g .

It is possible to generalize this argument to nonseparable spaces. Alternatively, a geometric proof is well-known. WLOG, the norm $\sup_{\|f\| \leq 1} \ell(f)$ of ℓ is 1. For every $\varepsilon \in (0, 1)$ and f such that $\ell(f) \geq 1 - \varepsilon$ we have

$$(a) \quad |\ell(g) - \langle f, g \rangle| \leq \sqrt{2\varepsilon} \text{ for all } g \text{ of norm } \leq 1;$$

$$(b) \quad \|f - g\| \leq 2\sqrt{2\varepsilon - \varepsilon^2} \text{ for all } g \text{ of norm } \leq 1 \text{ such that } \ell(g) \geq 1 - \varepsilon;$$

just elementary geometry on the Euclidean plane containing f and g .



Thus, every sequence $(f_n)_n$ such that $\ell(f_n) \rightarrow 1$, being Cauchy sequence, converges to some f , and $\forall g \in L_2(\mu) \quad \ell(g) = \langle f, g \rangle$.

Theorem 9b2 is thus proved.

9b7 Remark. Let (X, S) and (Y, T) be measurable spaces, and $\varphi : X \rightarrow Y$ measurable map. If measures μ_1, ν_1 on (X, S) satisfy $\nu_1 \ll \mu_1$, then pushforward measures $\mu_2 = \varphi_*\mu_1, \nu_2 = \varphi_*\nu_1$ satisfy $\nu_2 \ll \mu_2$ (think, why). Therefore, every measure of the form $\varphi_*(f \cdot \mu)$ is also of the form $g \cdot \varphi_*\mu$.

9b8 Definition. Two measures μ, ν on a measure space (X, S) are *mutually singular* (in symbols, $\mu \perp \nu$) if there exists $A \in S$ such that $\mu(A) = 0$ and $\nu(X \setminus A) = 0$.

See 3d5 for a nonatomic measure on $[0, 1]$ that is singular to Lebesgue measure.

9b9 Exercise. Two σ -finite measures μ, ν on (X, S) are mutually singular if and only if $\frac{d\mu}{d(\mu+\nu)} \in \{0, 1\}$ a.e.

Prove it.

9b10 Theorem (Lebesgue's decomposition theorem). Let (X, S, μ) be a σ -finite measure space, and ν a σ -finite measure on (X, S) . Then ν can be expressed uniquely as a sum of two measures, $\nu = \nu_a + \nu_s$, where $\nu_a \ll \mu$ and $\nu_s \perp \mu$.

9b11 Exercise. Prove Theorem 9b10.¹

9c Conditioning

9c1 Definition. Given a probability space (Ω, \mathcal{F}, P) , a measurable space (E, S) and a measurable map $\varphi : \Omega \rightarrow E$ from (Ω, \mathcal{F}) to (E, S) , we define the *conditional expectation* $\mathbb{E}(X|\varphi)$ of an integrable $X : \Omega \rightarrow \mathbb{R}$

(a) for $X : \Omega \rightarrow [0, \infty)$, as a measurable $g : E \rightarrow [0, \infty)$ such that $\varphi_*(X \cdot P) = g \cdot \varphi_*P$;

(b) in general, by $\mathbb{E}(X|\varphi) = \mathbb{E}(X_+|\varphi) - \mathbb{E}(X_-|\varphi)$.

9c2 Remark. Existence of $\mathbb{E}(X|\varphi)$ is ensured by 9b7, uniqueness (up to equivalence) by 9b5. The equivalence class of $\mathbb{E}(X|\varphi)$ is uniquely determined by the equivalence class of X .

9c3 Exercise. The conditional expectation is a linear operator from $L_1(P)$ to $L_1(\varphi_*P)$, and $\|\mathbb{E}(X|\varphi)\| \leq \|X\|$, and $\mathbb{E}_1(\mathbb{E}(X|\varphi)) = \mathbb{E}X$ (where \mathbb{E}_1 is the integral w.r.t. φ_*P).

Prove it.²

¹Hint: consider $\frac{d\mu}{d(\mu+\nu)}$.

²Recall the proof of 4d2.

Some convenient notation:

$$(9c4) \quad \mathbb{P}(A|\varphi) = \mathbb{E}(\mathbb{1}_A|\varphi) \quad \text{for } A \in \mathcal{F} \quad (\text{“conditional probability”});$$

$$(9c5) \quad \mathbb{E}(X|\varphi = b) = \mathbb{E}(X|\varphi)(b) \quad \text{for } b \in E.$$

By 4c21, $\varphi_*((f \circ \varphi) \cdot P) = f \cdot \varphi_*P$; applying this to f_+, f_- we get for a φ_*P -integrable f

$$(9c6) \quad \mathbb{E}(f \circ \varphi|\varphi) = f,$$

that is,

$$(9c7) \quad \mathbb{E}(f(\varphi)|\varphi = b) = f(b).$$

Moreover, assuming integrability of X , $f \circ \varphi$ and $(f \circ \varphi)X$,

$$(9c8) \quad \mathbb{E}((f \circ \varphi)X|\varphi) = f \mathbb{E}(X|\varphi),$$

since for $X \geq 0$, $f \geq 0$ (otherwise, take f_+, f_-, X_+, X_-)

$$\begin{aligned} \varphi_*((f \circ \varphi)X \cdot P) &= \varphi_*((f \circ \varphi) \cdot (X \cdot P)) = f \cdot \varphi_*(X \cdot P) = \\ &= f \cdot (\mathbb{E}(X|\varphi) \cdot \varphi_*P) = (f \mathbb{E}(X|\varphi)) \cdot \varphi_*P. \end{aligned}$$

That is,

$$(9c9) \quad \mathbb{E}(f(\varphi)X|\varphi = b) = f(b) \mathbb{E}(X|\varphi = b)$$

(“taking out what is known”, or “pulling out known factors”).

The equality $\varphi_*(X \cdot P) = g \cdot \varphi_*P$ may be rewritten as

$$(9c10) \quad \int_{\varphi^{-1}(B)} X \, dP = \int_B g \, d\varphi_*P \quad \text{for all } B \in S$$

or, using (4c22), as

$$(9c11) \quad \int_{\varphi^{-1}(B)} X \, dP = \int_{\varphi^{-1}(B)} g \circ \varphi \, dP \quad \text{for all } B \in S.$$

Introducing the σ -algebra \mathcal{F}_φ (“generated by φ ”) by

$$\mathcal{F}_\varphi = \{\varphi^{-1}(B) : B \in S\},$$

we rewrite (9c11) as $\int_A X \, dP = \int_A g \circ \varphi \, dP$ for all $A \in \mathcal{F}_\varphi$, that is, $(X \cdot P)|_{\mathcal{F}_\varphi} = ((g \circ \varphi) \cdot P)|_{\mathcal{F}_\varphi}$; also, $g \circ \varphi$ is measurable on $(\Omega, \mathcal{F}_\varphi)$.

Thus, we may forget φ , consider instead a sub- σ -algebra $\mathcal{F}_1 \subset \mathcal{F}$, and define $\mathbb{E}(X|\mathcal{F}_1)$ as an integrable function on $(\Omega, \mathcal{F}_1, P_{\mathcal{F}_1})$ such that¹

$$(X \cdot P)|_{\mathcal{F}_1} = \mathbb{E}(X|\mathcal{F}_1) \cdot P|_{\mathcal{F}_1} \quad \text{for } X \geq 0,$$

and in general,

$$\int_A X \, dP = \int_A \mathbb{E}(X|\mathcal{F}_1) \, dP \quad \text{for all } A \in \mathcal{F}_1,$$

that is,

$$\mathbb{E}(X \mathbb{1}_A) = \mathbb{E}(\mathbb{E}(X|\mathcal{F}_1) \mathbb{1}_A) \quad \text{for all } A \in \mathcal{F}_1.$$

This approach may seem to be more general, but in fact, it is not. Given $\mathcal{F}_1 \subset \mathcal{F}$, we may take $(E, S) = (\Omega, \mathcal{F}_1)$ and $\varphi = \text{id}$. Thus, all formulas written in terms of $\mathbb{E}(\cdot|\varphi)$ may be rewritten (and still hold!) in terms of $\mathbb{E}(\cdot|\mathcal{F}_1)$. In particular, (9c6)–(9c9) turn into

$$(9c12) \quad \mathbb{E}(f|\mathcal{F}_1) = f \quad \text{for } \mathcal{F}_1\text{-measurable, integrable } f;$$

$$(9c13) \quad \mathbb{E}(fX|\mathcal{F}_1) = f \mathbb{E}(X|\mathcal{F}_1) \quad \text{for } \mathcal{F}_1\text{-measurable } f$$

(integrability of f , X and fX is assumed, integrability of $f \mathbb{E}(X|\mathcal{F}_1)$ follows).

Also, by 9c3, the conditional expectation is a linear operator $L_1(\Omega, \mathcal{F}, P) \rightarrow L_1(\Omega, \mathcal{F}_1, P|_{\mathcal{F}_1}) \subset L_1(\Omega, \mathcal{F}, P)$, and

$$(9c14) \quad \|\mathbb{E}(X|\mathcal{F}_1)\|_1 \leq \|X\|_1,$$

$$(9c15) \quad \mathbb{E}(\mathbb{E}(X|\mathcal{F}_1)) = \mathbb{E}X$$

(“law of total² expectation”).

By 5f4, $L_2(P) \subset L_1(P)$. Let us consider $Y = \mathbb{E}(X|\mathcal{F}_1)$ for $X \in L_2(P)$. For every \mathcal{F}_1 -measurable $Z \in L_2(P)$ we know that XZ is integrable, and (9c13) gives $\mathbb{E}(ZX|\mathcal{F}_1) = Z\mathbb{E}(X|\mathcal{F}_1) = ZY$. Using (9c14), $\|ZY\|_1 \leq \|ZX\|_1 \leq \|Z\|_2 \|X\|_2$, which implies $\|Y\|_2 \leq \|X\|_2$ (take $Z_n \rightarrow Y$, $|Z_n| \leq |Y|$), thus, $Y \in L_2$. Using (9c15), $\mathbb{E}(ZX) = \mathbb{E}(ZY)$, that is, $\langle Z, X \rangle = \langle Z, Y \rangle$. We see that $X - Y$ is orthogonal to the subspace $L_2(\Omega, \mathcal{F}_1, P|_{\mathcal{F}_1})$ of $L_2(\Omega, \mathcal{F}, P)$, and Y belongs to this subspace, which shows that

$$(9c16) \quad \mathbb{E}(X|\mathcal{F}_1) \text{ is the orthogonal projection of } X \text{ to } L_2(\Omega, \mathcal{F}_1, P|_{\mathcal{F}_1})$$

(in other words, the best approximation...), whenever $X \in L_2(P)$. Taking into account that $L_2(P)$ is dense in $L_1(P)$ we may say that the conditional expectation is the orthogonal projection extended by continuity to $L_1(P)$.³

¹For a \mathcal{F}_1 -measurable f we have $\int f \, dP = \int f \, d(P|_{\mathcal{F}_1})$, as was noted before 4c24.

²Or “iterated”.

³The continuity in L_1 metric does not follow just from continuity in L_2 metric; specific properties of this operator are used.

9c17 Exercise. (a) Let $b \in E$ be an atom of φ_*P , that is, $\{b\} \in S$ and $P(\varphi^{-1}(b)) > 0$. Then

$$\mathbb{P}(A|\varphi = b) = \frac{P(A \cap \varphi^{-1}(b))}{P(\varphi^{-1}(b))}.$$

(b) Let B be an atom of $P|_{\mathcal{F}_1}$, that is, $B \in \mathcal{F}_1$, $P(B) > 0$, and

$$\forall C \in \mathcal{F}_1 \quad (C \subset B \implies P(C) \in \{0, P(B)\}).$$

Then

$$\mathbb{P}(A|\mathcal{F}_1) = \frac{P(A \cap B)}{P(B)} \quad \text{on } B.$$

Prove it.

We see that an atom leads to a conditional measure,

$$P_b : A \mapsto \frac{P(A \cap \varphi^{-1}(b))}{P(\varphi^{-1}(b))}, \quad \text{or} \quad P_B : A \mapsto \frac{P(A \cap B)}{P(B)},$$

a probability measure concentrated on $\varphi^{-1}(b)$, or B ; and in this case, the conditional expectation is the integral w.r.t. the conditional measure,

$$\mathbb{E}(X|\varphi = b) = \int X \, dP_b, \quad \text{or} \quad \mathbb{E}(X|\mathcal{F}_1) = \int X \, dP_B \quad \text{on } B$$

(check it). Also, an atom is “self-sufficient”: in order to know its conditional measure we need to know only B (or $\varphi^{-1}(b)$) rather than the whole \mathcal{F}_1 (or φ).

In the general theory, existence of conditional measures is problematic.¹ But in specific (non-pathological) examples it usually exists and may be calculated (more or less) explicitly.

9c18 Example. The special case treated in Sect. 6d: $(\Omega, \mathcal{F}, P) = (\Omega_1, \mathcal{F}_1, P_1) \times (\Omega_2, \mathcal{F}_2, P_2)$ and $\varphi(\omega_1, \omega_2) = \omega_1$. The conditional measure P_{ω_1} is the image of P_2 under the embedding $\omega_2 \mapsto (\omega_1, \omega_2)$.

9c19 Example. Let Ω be the unit disk $\{(x, y) : x^2 + y^2 < 1\}$ on \mathbb{R}^2 , with the Lebesgue σ -algebra \mathcal{F} and the uniform distribution P (with the constant density $1/\pi$); and let $\varphi(x, y)$ be the polar angle,

$$\begin{array}{l} x = r \cos \theta \\ y = r \sin \theta \end{array} \quad \text{where} \quad \begin{array}{l} r = \sqrt{x^2 + y^2} \\ \theta = \varphi(x, y). \end{array}$$

¹It holds for standard probability spaces, and may fail otherwise.

(We neglect the origin.)

We have a homeomorphism (moreover, diffeomorphism) between two open sets in \mathbb{R}^2 :

$$\alpha : (0, 1) \times (-\pi, \pi) \rightarrow \Omega \setminus ((-1, 0] \times \{0\}) . \quad \alpha(r, \theta) = (x, y) .$$

Using elementary geometry,

$$P(\alpha((0, r) \times (\theta_1, \theta_2))) = \frac{1}{\pi} \frac{\theta_2 - \theta_1}{2} r^2 = \left(\int_{\theta_1}^{\theta_2} \frac{d\theta}{2\pi} \right) \left(\int_0^r 2\rho \, d\rho \right)$$

for $-\pi \leq \theta_1 \leq \theta_2 \leq \pi$ and $0 \leq r \leq 1$, which means that P is the image of the product measure $\frac{d\theta}{2\pi} 2r \, dr$ on $(0, 1) \times (-\pi, \pi)$. (Indeed, the latter measure coincides with $(\alpha^{-1})_* P$ on the algebra generated by boxes.)¹

Neglecting the null set $(-1, 0] \times \{0\} \subset \Omega$ we see that conditioning on the map $\varphi : \Omega \rightarrow (-\pi, \pi)$, $\varphi(x, y) = \theta$, is equivalent² to conditioning on the projection $(0, 1) \times (-\pi, \pi) \rightarrow (-\pi, \pi)$, $(r, \theta) \mapsto \theta$. Treated as random variables, r and θ are independent, and the distribution of r has the density $2r$; the same is the conditional distribution of r given θ . Thus,

$$\begin{aligned} \mathbb{E}(X | \varphi = \theta) &= \int_0^1 X(r \cos \theta, r \sin \theta) 2r \, dr ; \\ \mathbb{E}(X | \mathcal{F}_\varphi)(x, y) &= \int_0^1 X\left(\frac{rx}{\sqrt{x^2 + y^2}}, \frac{ry}{\sqrt{x^2 + y^2}}\right) 2r \, dr . \end{aligned}$$

9c20 Example. Still, the same Ω (the disk), \mathcal{F} and P , but now let φ be the projection $(x, y) \mapsto x$ from Ω to $(-1, 1)$.

Treating P as a measure on \mathbb{R}^2 we see that it is not a product measure (think, why), but it has a density $\frac{1}{\pi} \mathbb{1}_\Omega$ w.r.t. the product measure $m_2 = m_1 \times m_1$. Thus,

$$\int X \, dP = \int dx \int dy X(x, y) \frac{1}{\pi} \mathbb{1}_\Omega(x, y) ;$$

for $X \geq 0$ we see that $\varphi_*(X \cdot P)$ has the density $x \mapsto \int X(x, y) \frac{1}{\pi} \mathbb{1}_\Omega(x, y) \, dy$ w.r.t. m_1 . In particular, taking $X = 1$ we see that $\varphi_*(P)$ has the density

¹By the way, this is a special case of a well-known change of variable theorem from Analysis-3: if $U, V \subset \mathbb{R}^d$ are open sets and $\varphi : U \rightarrow V$ a diffeomorphism, then $\int_U (f \circ \varphi) |\det D\varphi| \, dm = \int_V f \, dm$ for every compactly supported continuous function f on V . A limiting procedure gives $\int_B |\det D\varphi| \, dm = m(\varphi(B))$ for every box B such that $\bar{B} \subset U$. It follows that $(\varphi^{-1})_* m = |\det D\varphi| \cdot m$ on every B , and therefore, on the whole U .

²See also 9c22.

$x \mapsto \int \frac{1}{\pi} \mathbb{1}_\Omega(x, y) dy = \frac{2}{\pi} \sqrt{1-x^2}$ (and 0 if $x^2 > 1$) w.r.t. m_1 . Thus, $\varphi_*(X \cdot P)$ has the density¹

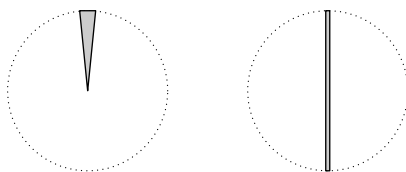
$$\frac{\pi}{2\sqrt{1-x^2}} \int X(x, y) \frac{1}{\pi} \mathbb{1}_\Omega(x, y) dy = \frac{1}{2\sqrt{1-x^2}} \int_{-\sqrt{1-x^2}}^{+\sqrt{1-x^2}} X(x, y) dy$$

w.r.t. $\varphi_*(P)$. It means that

$$\mathbb{E}(X | \varphi = x) = \frac{1}{2\sqrt{1-x^2}} \int_{-\sqrt{1-x^2}}^{+\sqrt{1-x^2}} X(x, y) dy \quad \text{for } -1 < x < 1$$

(just the mean value on the section) for $X \geq 0$, and therefore for arbitrary X .

We observe another manifestation of the Borel-Kolmogorov paradox: by 9c19, the conditional density of y given $\theta = \pi/2$ is proportional to y , while by 9c20, the conditional density of y given $x = 0$ is constant.



As noted after 9c17, a condition of positive probability is self-sufficient. Now we see that a condition of zero probability is not. Being unable to divide by zero, we need a limiting procedure, involving a neighborhood of the given condition.

9c21 Exercise. Let $(\Omega, \mathcal{F}, Q) = (\Omega_1, \mathcal{F}_1, Q_1) \times (\Omega_2, \mathcal{F}_2, Q_2)$ (probability spaces), $P \ll Q$ another probability measure on (Ω, \mathcal{F}) , and $\varphi : \Omega \rightarrow \Omega_1$ the projection $\varphi(\omega_1, \omega_2) = \omega_1$. Then, on (Ω, \mathcal{F}, P) , the conditioning is

$$\mathbb{E}(X | \varphi = \omega_1) = \int_{\Omega_2} \frac{f(\omega_1, \cdot)}{f_1(\omega_1)} X(\omega_1, \cdot) dQ_2$$

where $f = \frac{dP}{dQ}$ and $f_1(\omega_1) = \int_{\Omega_2} f(\omega_1, \cdot) dQ_2$.

Formulate it accurately, and prove.²

In this case we have conditional measures, and moreover, conditional densities (w.r.t. Q_2 , not w.r.t. $Q_1 \times Q_2$).

¹Indeed, if $\nu = f \cdot \mu$, $0 < f < \infty$, and $\xi = g \cdot \mu$, then $\mu = \frac{1}{f} \cdot \nu$ and so $\xi = g \cdot (\frac{1}{f} \cdot \nu) = \frac{g}{f} \cdot \nu$.

²Hint: similar to 9c20; what about $f_1(\omega_1) = 0$?

9c22 Exercise. Let $(\Omega_1, \mathcal{F}_1, P_1)$ and $(\Omega_2, \mathcal{F}_2, P_2)$ be probability spaces, $\alpha : \Omega_1 \rightarrow \Omega_2$ a measure preserving map, (E, S) a measurable space, and $\varphi : \Omega_2 \rightarrow E$ a measurable map from $(\Omega_2, \mathcal{F}_2)$ to (E, S) . Then

$$\mathbb{E}(X \circ \alpha | \varphi \circ \alpha) = \mathbb{E}(X | \varphi)$$

for all $X \in L_1(P_2)$.

Prove it.

9c23 Exercise. Let the joint distribution $P_{X,Y}$ of two random variables X, Y be absolutely continuous (w.r.t. the two-dimensional Lebesgue measure m_2). Then

$$\mathbb{E}(Y | X = x) = \int y p_{Y|X=x}(y) dy$$

where

$$p_{Y|X=x}(y) = \frac{p_{X,Y}(x, y)}{p_X(x)}, \quad p_X(x) = \int p_{X,Y}(x, y) dy, \quad p_{X,Y} = \frac{dP_{X,Y}}{dm_2}.$$

Formulate it accurately, and prove.¹

Back to the “great circle puzzle” of Sect. 9a. Suppose that a random point is distributed uniformly on the sphere. What is the conditional distribution on a given great circle?

This question cannot be answered without asking first, how is this great circle obtained from the random point.²

One case: there is a special (nonrandom) point (“the North Pole”), and we are given the great circle through the North Pole and the random point. Then the conditional density is $\frac{1}{2} \sin \theta$, where θ is the angle to the North Pole.

Another case: the given great circle is chosen at random among all great circles containing the random point. Equivalently: the “North Pole” is chosen at random, uniformly, independently of the random point. Then the conditional density is constant, $\frac{1}{2\pi}$.³

Having conditional measures, it is tempting to define conditional expectation of X as the integral w.r.t. the conditional measure, requiring just integrability of X w.r.t. almost all conditional measures (which is necessary and

¹Hint: 9c21, 9c22.

²“... the term ‘great circle’ is ambiguous until we specify what limiting operation is to produce it. The intuitive symmetry argument presupposes the equatorial limit; yet one eating slices of an orange might presuppose the other.” E.T. Jaynes (quote from Wikipedia).

³The proof involves the invariant measure on the group of rotations (“Haar measure”).

not sufficient for unconditional integrability, since the conditional expectation of $|X|$ need not be integrable). Then, however, strange things happen. For example, it may be that $\mathbb{E}(X|\mathcal{F}_1) > 0$ a.s., but $\mathbb{E}(X|\mathcal{F}_2) < 0$ a.s. An example (sketch): $\mathbb{P}(X = n, Y = n+1) = \mathbb{P}(X = n+1, Y = n) = 0.5p^n(1-p)$ for $n = 0, 1, 2, \dots$; then $\mathbb{E}(a^Y|X = x) = \frac{pa+a^{-1}}{1+p}a^x$ for $x = 1, 2, \dots$; we take $ap > 1$ and get $\mathbb{E}(a^Y|X) > a^X$ a.s., but also $\mathbb{E}(a^X|Y) > a^Y$ a.s.¹ Would you prefer to gain a^X or a^Y in a game?

9d More on absolute continuity

9d1 Proposition. Let (X, S, μ) be a measure space, and ν a finite measure on (X, S) . Then

$$\nu \ll \mu \iff \forall \varepsilon > 0 \exists \delta > 0 \forall A \in S (\mu(A) < \delta \implies \nu(A) < \varepsilon).$$

Proof. “ \Leftarrow ” is easy: $\mu(A) = 0$ implies $\forall \varepsilon \nu(A) < \varepsilon$.

“ \Rightarrow ”: Otherwise we have ε and $A_n \in S$ such that $\mu(A_n) \rightarrow 0$ but $\nu(A_n) \geq \varepsilon$. WLOG, $\sum_n \mu(A_n) < \infty$. Taking $B_n = A_n \cup A_{n+1} \cup \dots$ we have $\mu(B_n) \rightarrow 0$, $\nu(B_n) \geq \varepsilon$, and $B_n \downarrow B$ for some B . Thus, $\mu(B) = 0$, but $\nu(B) \geq \varepsilon$ (due to finiteness of ν), in contradiction to $\nu \ll \mu$. \square

9d2 Proposition. Let (X, S, μ) be a measure space, $\mathcal{E} \subset S$ a generating algebra of sets, μ be \mathcal{E} - σ -finite,² and ν a finite measure on (X, S) . Then

$$\nu \ll \mu \iff \forall \varepsilon > 0 \exists \delta > 0 \forall E \in \mathcal{E} (\mu(E) < \delta \implies \nu(E) < \varepsilon).$$

Proof. “ \Rightarrow ” follows easily from 9d1 (since $\mathcal{E} \subset S$).

“ \Leftarrow ”: By 9d1 it is sufficient to prove that $\mu(A) < \frac{1}{2}\delta \implies \nu(A) < 2\varepsilon$. Given $A \in S$ such that $\mu(A) < \frac{1}{2}\delta$, 7b4 applies to $\mu + \nu$ (think, why) giving $E \in \mathcal{E}$ such that $(\mu + \nu)(E \Delta A) < \min(\frac{1}{2}\delta, \varepsilon)$. Then $\mu(E) \leq \mu(A) + \mu(E \Delta A) < \frac{1}{2}\delta + \frac{1}{2}\delta = \delta$, whence $\nu(E) < \varepsilon$ and $\nu(A) \leq \nu(E) + \nu(E \Delta A) < \varepsilon + \varepsilon = 2\varepsilon$. \square

In particular, we may take (X, S, μ) to be \mathbb{R} (or \mathbb{R}^d) with Lebesgue measure (or arbitrary locally finite measure), and \mathcal{E} the algebra generated by intervals (or boxes).

9d3 Definition. A continuous function $F : [a, b] \rightarrow \mathbb{R}$ is *absolutely continuous*, if for every $\varepsilon > 0$ there exists $\delta > 0$ such that for every n and disjoint intervals $(a_1, b_1), \dots, (a_n, b_n) \subset [a, b]$,

$$\sum_{k=1}^n (b_k - a_k) < \delta \implies \sum_{k=1}^n |F(b_k) - F(a_k)| < \varepsilon.$$

¹Recall 1b1: $-\frac{1}{2} = \frac{1}{2} - 1 + 1 - 1 + \dots = +\frac{1}{2}$.

²As defined before 7b4.

9d4 Proposition. A finite nonatomic measure μ on \mathbb{R} is absolutely continuous (w.r.t. Lebesgue measure) if and only if the function

$$F_\mu : x \mapsto \mu((-\infty, x])$$

is absolutely continuous on every $[a, b]$.

9d5 Exercise. Prove Prop. 9d4.

9d6 Corollary. An increasing continuous function F on $[a, b]$ is absolutely continuous if and only if there exists $f \in L_1[a, b]$ such that $F(x) = \int_a^x f \, dm$ for all $x \in [a, b]$.

Taking $F = F_\mu$ for μ of 3d5 we get a continuous but not absolutely continuous increasing function on $[0, 1]$.¹

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¹Known as “Cantor function”, “Cantor ternary function”, “Lebesgue’s singular function”, “the Cantor-Vitali function”, “the Cantor staircase function” and even “the Devil’s staircase”, see Wikipedia.